

Audio Board

User Manual

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Chapter 1. Audio Board

1. Overview

The Audio Board provides a high speed DAC, with an AF amplifier and speaker, capable of playing voice and music samples. The Audio Board has an on-board DataFlash for storing audio samples. The board also provides the capability to control the volume through software, using a digital potentiometer.

2. Board Features

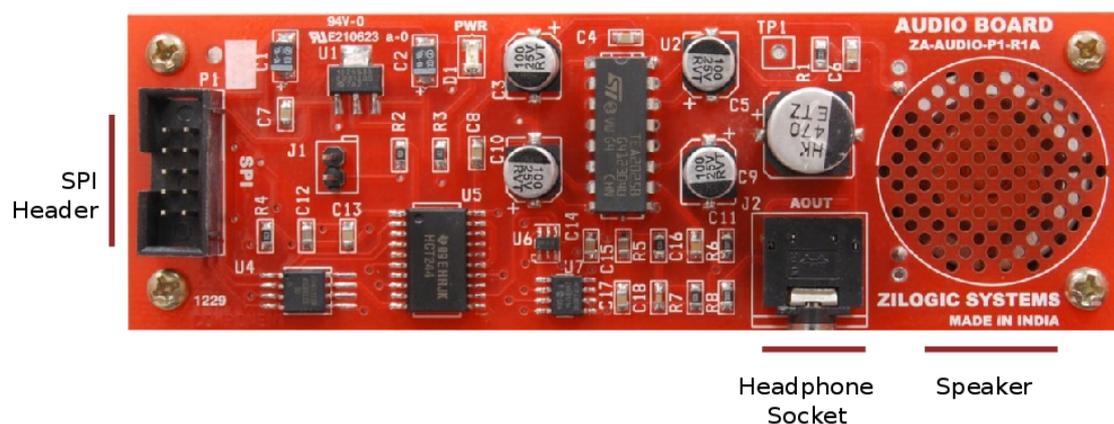
The Audio Board has the following features

- MCP4801, 8-bit SPI DAC
- AT45DB321D, 4MB DataFlash
- MCP4021, non-volatile digital potentiometer for volume control
- On board speaker
- Headphone jack
- Standard 0.1" FRC header for connection to MCU
- Ready to go with Zilogic motherboards

3. Locating Components

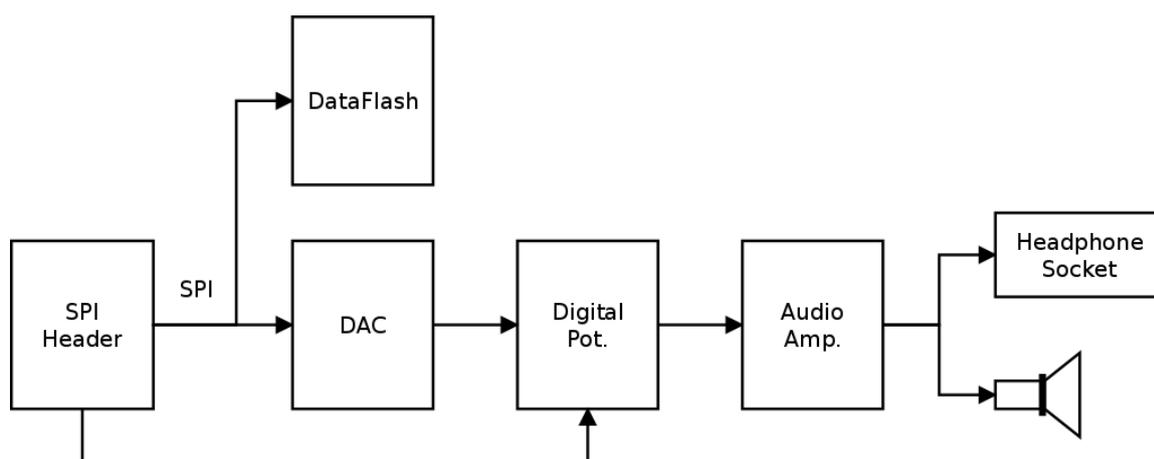
The location of the components on the board is indicated in the following diagram.

Figure 1.1. Front View



4. Block Diagram

The devices available on the board, is shown in the following block diagram. Each device is described in detail in the following sections.

Figure 1.2. Block Diagram

5. Power Supply

The Audio Board is powered from the motherboard through the **VCC** on the 10-pin FRC header. Detailed power supply specifications are available in section Specifications.

6. SPI Interface

The digital audio samples are provided to the DAC through a SPI interface. The DataFlash is also accessed through the same SPI. The DAC is selected by **CS1**. The DataFlash is selected by **CS0**.

The volume is controlled through a simple up/down serial interface, by two TTL inputs **VOL_CS** and **VOL_U/D**. The state of the **VOL_U/D** at the falling edge of **VOL_CS** determines if increment or decrement is desired. Subsequent rising edges in **VOL_U/D** indicates the amount of steps to increase/decrease.

7. Connectors and Headers

7.1. INPUT Connector

The audio board can be interfaced through the **INPUTS** SPI bus connector. The signal details are given below.

Table 1.1. SPI FRC-10 Connector

Pin #	Signal	Description
1	VCC	Power supply
2	SCK	Serial Clock
3	MISO	Serial Output
4	MOSI	Serial Input
5	CS0	Chip Select for DataFlash
6	CS1	Chip Select for DAC
7	FLASH_RST	DataFlash reset
8	VOL_CS	Chip Select for Digital Potentiometer
9	VOL_U/D	Increment/Decrement
10	GND	Ground

8. Specifications

Parameter	Value	Condition
VCC		
Voltage	5V	
Max. Current	200mA	
Digital Inputs		
Input Low Voltage	0.0 - 0.8V	
Input High Voltage	3.5 - 5.0V	

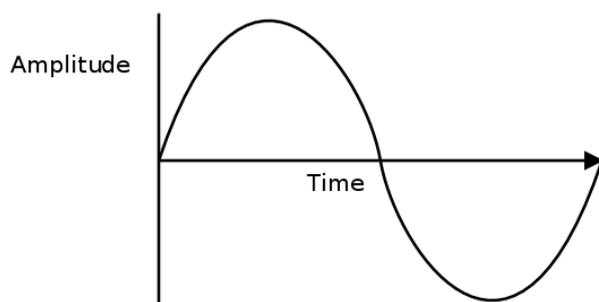
Chapter 2. Board Usage

1. Audio Basics

An audio signal when captured through a microphone is available as a time varying voltage, as shown in Figure 2.1, "Signal". When such signals are to be stored in a computer, they have to be digitized. The digitization is a two step process.

1. Sampling
2. Quantization

Figure 2.1. Signal



Sampling. A time varying voltage signal, has infinite no. of values between two time points, say second 0 and second 1. As such it is impossible to store these values in a computer. Instead we approximate the signal by looking at the signal periodically, say every 10ms. We note the voltage at 0ms, 10ms, 20ms, 30ms and so on. An example is shown in Figure 2.2, "Sampling and Quantization". This way of storing only specific time points of a signal is called Sampling. If the sampling period is T , $1/T$ is called the Sampling Frequency.

The only restriction on the sampling frequency, is that, the sampling frequency should be twice the maximum frequency in the signal, for the signal to be completely reproduced.

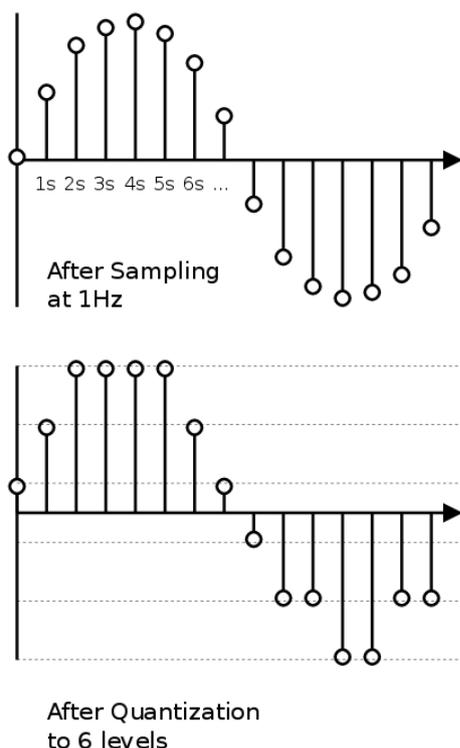
Quantization. A time varying voltage signal, that varies between say -3V and 3V, has infinite no. of values between -3V and 3V. Here again we restrict ourselves to a set of values that are equally spaced between -3V and 3V. For example, we might choose a spacing of 1V, and hence will store only -3V, -2V, -1V, 0V, 1V, etc. If at a time point we read a value of 0.8V, then we round it off to 1V, and store 1V instead. Each of these voltages is given a binary representation, as shown in the following table. It is this binary representation that actually gets stored.

Voltage	Binary Representation
-3V	001
-2V	010
-1V	011
0V	100
1V	101
2V	110
3V	111

This way of restricting ourselves to a set of values, is called Quantization. The no. of values we restrict ourselves to determines the accuracy with which the signal has been captured, and the

accuracy with which it can be reproduced. The more the no. of levels more the no. of bits required to represent each sample. The no. of bits required to represent a sample is called the Bit Depth or Bits Per Sample.

Figure 2.2. Sampling and Quantization



The following table indicates the sampling frequency and the audio bit depth, for various different audio quality.

Quality	Sampling Frequency	Bits Per Sample
Telephone	8KHz	8
AM Audio	11.025KHz	8
FM Audio	22.050KHz	16
CD	44.1KHz	16
DVD	48KHz	16

2. Compression

A five minute stereo audio signal stored in CD quality, will occupy about 50 MB. Fortunately, audio data can easily be compressed. An MP3 or OGG compression will result in just 5 MB of compressed data. Uncompressed audio is generally called PCM. And when such PCM data is stored in a file without any headers, it is called a **Raw PCM** file.

3. Creating Raw PCM

Audio is generally stored in a compressed format like MP3. But these need to be converted to Raw PCM before it can be sent to the Audio Board. The Audio Board can play audio with the following parameters:

- Bits Per Sample: 8

- Sampling Frequency: 8kHz
- Channels: 1

A Raw PCM file with these parameters can be created using tools like SOund eXchange (SOX), FFmpeg, etc.

4. Pseudocode Functions

The pseudocode presented in the following sections, assume the existence of the following functions:

<code>spi_tx_rx(byte)</code>	Transmits an 8-bit integer <code>byte</code> to the SPI device, and returns the received byte as an 8-bit integer.
<code>gpio_set_pin(pin, state)</code>	Sets the state of an GPIO pin to high or low. <code>pin</code> is an integer, representing the GPIO pin no. <code>state</code> is an integer, 0 for low and 1 for high. The pin should have previously been configured to output mode.
<code>udelay(usecs)</code>	Generates a delay. <code>usecs</code> specifies the delay in microseconds.

5. Playing Raw PCM

The Raw PCM audio created using the instruction in Section 3, "Creating Raw PCM" can be stored in Flash memory of a micro-controller. The micro-controller can then play the audio by sending it to the DAC through a SPI interface. The following SPI parameters should be configured

- Transmit data on falling edge of the clock. `CPOL` = 0, `CPHA` = 0 or `CPOL` = 1, `CPHA` = 1.
- Transmit data bytes MSB first.

The following is the pseudocode to play a sample from the 8KHz 8-bit Raw PCM audio.

```
play_sample(sample):
    gpio_set_pin(CS1, 0)

    byte = (sample >> 4) & 0x0F ❶
    byte |= 0x10 ❷
    spi_tx_rx(byte)

    byte = (sample << 4) & 0xF0 ❸
    spi_tx_rx(byte)

    gpio_set_pin(CS1, 1)
```

- ❶ First byte contains the upper nibble, of the sample.
- ❷ Bit 4 indicates when set to 1 indicates Active Mode, and when set to 0 indicates Power Down mode.
- ❸ Second byte contains the lower nibble, of the sample.

The following is the pseudocode to play a sequence of samples the 8KHz 8-bit Raw PCM audio. The sampling period is 125us for 8KHz audio. Hence we send out one sample every 125us.

```
play(sample_list):
    for each sample in sample_list:
        play_sample(sample)
```

```
udelay(125)
```

6. Using DataFlash for Storage

As discussed earlier, Raw PCM audio data can easily consume lot of space. The Flash memory in micro-controllers is generally not sufficient to store such data. The Audio board provides a 4MB DataFlash for easy storage and retrieval of audio data.

The DataFlash itself is access through the SPI interface. Data is organized in a DataFlash in pages. Each page is 528 bytes in size.

The pseudocode to read a page from the DataFlash.

```
read_page(pageno, data):
    gpio_set_pin(CS0, 0)

    spi_tx_rx(0xD2)
    spi_tx_rx((pageno & 0x1FE0) >> 5)
    spi_tx_rx((pageno & 0x001F) << 3)
    spi_tx_rx(0)
    spi_tx_rx(0)
    spi_tx_rx(0)
    spi_tx_rx(0)
    spi_tx_rx(0)

    for i in 1 ... 528:
        data[i] = spi_tx_rx(0)

    gpio_set_pin(CS0, 1)
```

The pseudocode to write a page to the DataFlash.

```
wait_ready():
    gpio_set_pin(CS0, 0)

    spi_tx_rx(0xD7)

    ready = (spi_tx_rx(0) & 0x80)
    while ready == 0:
        ready = spi_tx_rx(0) & 0x80

    gpio_set_pin(CS0, 1)

write_page(pageno, data):
    gpio_set_pin(CS0, 0)

    spi_tx_rx(0x82)
    spi_tx_rx((pageno & 0x1FE0) >> 5)
    spi_tx_rx((pageno & 0x001F) << 3)
    spi_tx_rx(0)

    for i in 1 ... 528:
        spi_tx_rx(data[i])
```

```
gpio_set_pin(CS0, 1)
```

```
wait_ready()
```

Appendix A. Legal Information

1. Copying

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The warranties provided by Zilogic Systems in this Limited Hardware Warranty apply only to Hardware Products you purchase for your use, and not for resale. The term "Hardware Product" means a computing device with a specific function and limited configuration ability.

2.1. LIMITED HARDWARE WARRANTY

Zilogic Systems warrants that the hardware components of its Hardware Product shall be free from material defects in design, materials, and workmanship and will function, under normal use and circumstances, in accordance with the documentation provided, for a period of one (1) year from the date of purchase of the Hardware Product.

Your sole and exclusive remedy, and Zilogic Systems' sole and exclusive liability for defective hardware components, shall be that Zilogic Systems, subject to the terms and conditions of this Section, and solely upon confirmation of a defect or failure of a hardware component to perform as warranted, shall at its sole option, either repair or replace the nonconforming hardware component. All replacement parts furnished to you under this warranty shall be refurbished and equivalent to new, and shall be warranted as new for the remainder of the original warranty period. All defective parts, which have been replaced, shall become the property of Zilogic Systems. All defective parts that have been repaired shall remain your property.

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The foregoing warranties and remedies shall be void as to any Hardware Products damaged or rendered unserviceable by one or more of the following: (1) improper or inadequate maintenance by anyone other than Zilogic Systems or Zilogic Systems' authorized engineers, (2) interfacing supplied by anyone other than Zilogic Systems, (3) modifications, alterations or additions to the Hardware Products by personnel not certified by Zilogic Systems or Zilogic Systems' authorized engineers to perform such acts, or other unauthorized repair, installation or other causes beyond Zilogic Systems' control, (4) unreasonable refusal to agree with engineering change notice programs, (5) negligence by any person other than Zilogic Systems or Zilogic Systems' authorized engineers, (6) misuse, abuse, accident, electrical irregularity, theft, vandalism, fire, water or other peril, (7) damage caused by containment and/or operation outside the environmental specifications for the Hardware Products, (8) alteration or connection of the Hardware Products to other systems, equipment or devices (other than those specifically approved by Zilogic Systems) not in accordance to the board and on-board device specifications (9) any use that is inconsistent with the user manual supplied with the Hardware Product. The warranty period is not extended if Zilogic Systems repairs or replaces a warranted product or any parts. Zilogic Systems may change the availability of limited hardware warranties, at its discretion, but any changes will not be retroactive.

2.3. HARDWARE RETURN PROCEDURES

If a Hardware Product or one of its component parts does not function as warranted during the warranty period, and such nonconformance can be verified by Zilogic Systems, Zilogic Systems, at

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Transportation costs, if any, incurred in connection with the return of a defective item to Zilogic Systems shall be borne by You. Any transportation costs incurred in connection with the redelivery of a repaired or replacement item to You by Zilogic Systems shall be borne by Zilogic Systems; provided, however, that if Zilogic Systems determines, in its sole discretion, that the allegedly defective item is not covered by the terms and conditions of the warranty or that a warranty claim is made after the warranty period, the cost of the repair by Zilogic Systems, including all shipping expenses, shall be reimbursed by You.

2.4. HARDWARE REPLACEMENT PROCEDURES

Zilogic Systems will attempt to diagnose and resolve your problem over the phone or e-mail. Upon determination of the hardware issue is related to a malfunction of one of the Hardware Product components, an RMA process will be initiated by Zilogic Systems.

For Warranty Replacement service, it is required that you deliver the faulty unit to a location Zilogic Systems designates, and provide courier name and tracking number to Zilogic Systems. After the Faulty unit is returned to Zilogic Systems, Zilogic Systems will use commercially reasonable efforts to ship the replacement hardware within fourteen (14) business days. Actual delivery times may vary depending on availability of the spares and customer's location.

2.5. ADDITIONAL RESPONSIBILITIES

You agree:

- To provide Zilogic Systems or its partner with sufficient and safe access to your facilities to permit Zilogic Systems to fulfill its obligations.
- To ship back the faulty Hardware Product (or replaceable unit) suitably packaged, quoting the RMA number, to the Zilogic Systems designated location.
- You shall ship the faulty Hardware Product once Zilogic Systems approves the RMA and provide the courier name and tracking number.
- To securely erase from any Hardware Product you return to Zilogic Systems for any reason all programs and data not provided by Zilogic Systems with the Hardware Product. You acknowledge that in order to perform its responsibilities under this Limited Hardware Warranty, Zilogic Systems may ship all or part of the Hardware Product or its software to third party locations around the world, and you authorize Zilogic Systems to do so.

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